An Improved Reconstruction methods of Compressive Sensing Data Recovery in Wireless Sensor Networks

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Abstract

Energy consumption is a critical problem affecting the lifetime of wireless sensor networks (WSNs) in structural health monitoring (SHM). A huge original acquisition data was transmitted between nodes which occupy a large amount of communication bandwidth, and even lead to paralysis of WSNs. Thus, data compression to reduce network traffic and energy loss before transmission is necessary. A number of traditional techniques have proposed to solve this issue by sampling the full signal and then taking compression process. But it spends a lot of processing time. In this paper, we establish suitability compressive sensing (CS) to address some challenges using WSN. Through the improvement of reconstruction algorithm and the experimental demonstration, the application of this method could ensure the accuracy of the data as well as balance the network energy consumption. Moreover, it can also reduce the cost of data storage and transmission which makes a certain contribution to the quality for SHM.

Keywords: compressive sensing; wireless sensor networks; structural health monitoring; reconstruction algorithm

1. Introduction

With the development of WSN applications in structural health monitoring, data compression technology for SHM has been attracted a growing number of scholars’ attention. However, formerly, we arranged a large number of sensor nodes using a high frequency sampling rate for data acquisition and real-time monitoring, while as we all know that wireless sensor nodes have limited energy. Thus, it is necessary to get efficient compression in order to balance the network energy and reduce data storage or transmission cost.

SHM researchers proposed some compression algorithm [1-3] to achieve high compression efficiency. However, all methods above belong to the traditional framework for data compression which is firstly to sample the full signal and then compress it. Recently, a new data compression method named compressive sensing (CS)[4,5] which acquires data in compressed form directly by using special sensors has been presented initially used for image process. With the development of CS theory, it has been applied to WSNs, medical imaging, remote sensing [6], digital camera and so on. In the SHM, a few researchers [7, 8] applied it to the reconstruction of structural modal shape and analyzed plate structures.

A lot of studies have shown that CS theory is applicable for the structural monitoring narrowband signal compression which could enhance the robustness of the network data
transmission, and then it has a good prospect of application in the field of WSNs for SHM. Currently, though some CS applications have been existed in the SHM, it is still at the initial stage.

In this article, we mainly focused on the reconstruction methods research. Comparing with the existing methods, we proposed an improved reconstruction data algorithm of OMP in the CS application framework which is suitable for the SHM based on the WSN nodes. Through the experimental demonstration, it is able to ensure the data accuracy, balance the network energy consumption, and reduce the cost of data storage and transmission.

The rest of the paper is organized as follows. Section 2 describes the compressive sensing theory which is the basement of the CS application. The improved OMP that is Threshold Orthogonal Matching Pursuit (TOMP) algorithm is also proposed in Section 2. Section 3 presents the simulation results and analysis. And Section 4 concludes the paper.

2. Compressive Sensing Theory

Mainly, CS theory includes three parts: the sparse representation of the signal, the measurement matrix ensuring the data minimal information loss which should be satisfied the Restricted Isometry Property (RIP) and the reconstruction algorithm using the no-distortion observed value to reconstruct signals. Among them, reconstruction algorithm is an important factor in CS.

2.1. Signal Sparsity and the Sparse Representation

Signal sparsity is an important prerequisite for CS theoretical foundation. The essence of CS [9] is using an irrelevant measurement \((M \times N, M \ll N)\) with a matrix transform base (dimension) to put the original high-dimensional sparse signal or approximate sparse signal sequence \(N \times 1\) project in a low dimensional space (\(M\) dimension) to achieve signal compression.

Suppose that a measurement matrix \(\Phi \in \mathbb{R}^{M \times N} (M \ll N)\) is introduced to produce compressed sensing coefficients \(y\), then for a sparse signal \(x \in \mathbb{R}^N\), the linear measuring values in the measurement matrix \(y \in \mathbb{R}^M\) could be defined as (1), where \(\Phi\) is called a measurement matrix,

\[
y = \Phi x
\]  

(1)

However, we all know that nature signal is usually not absolutely sparse, but if it can be as approximate sparse signal in some transform domains such as Fourier domain, Wavelet domain and QuBo domain, we considered it is compressible signal. So through one of the orthogonal transformation \(\Psi\), we can achieve sparse representation (2).

\[
y = \Phi x = \Phi \Psi \alpha = \Theta \alpha
\]  

(2)

Where \(\Theta = \Phi \Psi\) is a \(M \times N\) sensing matrix, \(\Phi\) represents a \(M \times N\) measurement matrix and \(\Psi\) is a \(N \times N\) transformation matrix.

Formula(2) can be regarded as the linear projection of original signal \(x\) with \(\Phi\), and it could be also viewed as the linear projection of transform decomposition coefficients \(\alpha\) in \(\Theta\). If \(y\) and \(\Theta = \Phi \Psi\) meet with the RIP [10], \(K\)-sparse decomposition coefficients \(\alpha\) can be reconstructed by solving the \(l_0\) norm [11] from \(y\) as (3).

\[
\hat{\alpha} = \arg \min \| \alpha \|_0 \text{ s.t. } \Theta \alpha = y
\]  

(3)
where \( \hat{\alpha} \) is the only exact solution of decomposition coefficients \( \alpha \). Finally, exact solution \( \hat{x} \) can be obtained by reconstructing \( \hat{\alpha} \) under the orthogonal transform basis \( \Psi \) shown as (4):

\[
\hat{x} = \Psi \hat{\alpha}
\]  

(4)

2.2. Measurement Matrix Selections in CS

In the exact solution procedure to reconstruct original signal, sensing matrix \( \Theta = \Phi \Psi \) must meet the RIP which is proposed by Candes and Tao [10], and its definition is as follows:

Definition, Introducing any K sparse signal \( x \) and constant \( \delta_\kappa \in (0,1) \), sensing matrix \( \Theta \) should be fulfill with the equation (5):

\[
1 - \delta_\kappa \leq \frac{\| \Theta x \|_2}{\| x \|_2} \leq 1 + \delta_\kappa
\]  

(5)

To further demonstrate the intrinsic relationship between \( \Psi \) and \( \Phi \) while \( \Theta = \Phi \Psi \) met with the RIP, Baraniuk [12] proposed that the equivalence condition of the RIP which is \( \Phi \) irrelevant with \( \Psi \), i.e., the \( \Theta \) row vector cannot be represented by \( \Psi \) column vector, and the \( \Psi \) row vector cannot be represented by \( \Theta \) column vector.

Therefore, we select tectonic \( \Phi \) measurement matrix in the orthogonal base matrix \( \Psi \) which is fixed to make \( \Theta = \Phi \Psi \) satisfy with RIP in this article.

2.3. Reconstruction Algorithm Selection in CS

Reconstruction algorithms are CS theory’s core which using the value of the measurement vector \( y \) in M dimension to reconstruct the sparse signal in the length N. Candes proved that the signal reconstruction problem can be solved by solving the minimum \( l_0 \) norm which is shown on the formula (3), so that all signal reconstructions which solved by the \( l_0 \) norm can be resolved. Currently, the algorithm is mainly divided into three categories which are greedy algorithm [13, 14], convex optimization algorithms[15] and the sparse Bayesian statistical optimization algorithm[16].

Greedy Pursuit algorithm is selected a local optimal solution by each iteration to gradually approximate with original signals which made the reconstruction realization simply and fast. So it is suitable for the lower dimension small-scale signal problem. The most typical algorithms are Matching Pursuit (MP) algorithm [13] and Orthogonal Matching Pursuit (OMP) algorithm [14]. In this paper, we improved the OMP algorithm and used it as the stabled reconstruction method.

2.4. Improved OMP Algorithm (TOMP)

We improved the OMP algorithm and used it as the stabled reconstruction method which had a faster convergence. Table 1 shows the improved algorithm which called the TOMP (Threshold Orthogonal Matching Pursuit).

Table 1. TOMP Algorithm

<table>
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<tr>
<th>Algorithm 1 TOMP algorithm for the signal reconstruction</th>
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<td><strong>Input:</strong> residuals ( r_0=v ), Index set ( \Lambda_0=\emptyset ), Iteration count ( t=1 );</td>
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<tr>
<td><strong>Output:</strong> the elements in ( \Lambda_m ) which are the nonzero value indicators of the recovery signal ( x^* ), and noticing that the ( \lambda_j )-th element value in the ( s^* ) is equal to</td>
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the j-th element value in xt.

**Step 1:** Find indicator λt, to meet the following optimization problem: $\lambda t = \arg \max_{j=1, \ldots, d} |<r_{t-1}, \phi_j>|$.

**Step 2:** Expansion of the index set $\Lambda t = \Lambda_{t-1} \cup \{\lambda t\}$ and the matrix $\Phi t = [\Phi_{t-1} \phi_{\lambda t}]$, $\Phi 0$ is a empty matrix;

**Step 3:** Solving the Least squares problem: $x t = \arg \min x ||v - \Phi tx||^2$;

**Step 4:** Calculate the new signal estimation and residuals: $a t = \Phi t x t$, $r t = v - a t$, $t = t+1$;

**Step 5:** Given the reconstruction error threshold $\delta$, if $||r t||^2 < \delta$, jump to output;

**Step 6:** if $t < K$, return to step 1.

Noticing that amusing we chose x signal which arbitrary sparsity is m from $R^d$ and $\Phi$ is a N×d dimension Gaussian matrix, then we execute the TOMP $v = \Phi x$. If the residuals ‘r m’ is equal to zero after m iteration, it is considered that TOMP could complete the recovery of the original signal x, otherwise this represents that TOMP algorithm is failure.

Compared with the OMP algorithm, TOMP has added the reconstruction error threshold $\delta$ which is determined by the demand for the actual structure of the health damage detection. For each iteration in the signal reconstruction process, it is necessary to compared the reconstructed result and the original one with $\delta$, if $||r t||^2 < \delta$, then we can stop the reconstruction and jump to output. In the other words, if it met with the demand that we can end prematurely instead of iterative K times. In a word, TOMP could improve the convergence speed of the algorithm effectively while maintaining the reconstruction accuracy which has improved the reconstruction efficiency.

3. Performance Evaluation

3.1. Evaluation Standards for CS Application in SHM

**Compression ratio (CR):** The compression ratio is one of the indicators to measure the degree of data compression whose definition is the compression ratio between the original signal data quantity and the compressed data amount written as the follows (6):

$$CR = \frac{N_o}{N_{co}}$$

(6)

Where $N_o, N_{co}$ denote the signal data quantity and compressed data amount. The larger the CR is, the better compression performance will be with smaller traffic load on the network.

**Reconstruction error $\xi$:** Reconstruction error is on behalf of the similarity degree of the reconstructed signal and the original one. It is an import indicator to measure the effects of data decompression after refactoring which formula is (7):

$$\xi = \frac{||\hat{x} - x||_2}{||x||_2}$$

(7)

Where $\hat{x}, x$ separately indicated the reconstructed signal and the original one. The smaller the reconstruction error is, the higher the data recovery accuracy of the compressed sensing reconstruction algorithm is.
3.2. Simulation Results

In order to get the effective and real data of the experiments, we designed a data acquisition experimental system which sensor node is a common node without compression function. The experimental system which is shown on the Figure 1 consists of a PXI data acquisition system, YE5850 charge amplifier, KH7602 broadband power amplifier and LF-21M rust-proof aluminum pasted piezoelectric patch. The data acquisition system PXI is usually for the gathering of the monitoring signal with the maximum sampling frequency 10MHz. The sampling frequency of this experiment is 1MHz and collected 1024 points.

Figure 1. Schematic Diagram of the Experimental Specimen

In the data collection process, the whole size of the original data is about 208M. And the original real data in structural health monitoring will be used to validate the compressed sensing technology. Besides, in this experimental verification process, we choose Gaussian random matrix as the measurement matrix which has the most irrelevant with any sparse base. Moreover, each element independently meets with (0, 1/N) normal distribution. Probability density function is (8):

\[ p(x) = \frac{1}{\sqrt{2\pi N}} e^{-x^2/2N} \]  

(8)

Figure 2 describes the process of the reconstruction for the original signal without noise which has been compressed by CS. The signal length is N=1024, and the hardware threshold method SORH='h' is adopted. Moreover the selection of the threshold value is based on the Stein unbiased risk estimation threshold (rigrsure) which is TPTR='rigrsure'. Let the Gaussian random matrix as the measurement matrix and transform base is the Haar wavelet orthogonal transform base. Reconstruction algorithm is TOMP.
It can be seen from Figure 2, the signal sparsity after thresholding is K=99; the number of observations is M=231 which dropped from the N-dimensional to M-dimensional; the CR is 1024/231=4.4329; and relative error of the reconstructed signal is ξ=0.0830 and the absolute error of the reconstructed signal with the original signal is during [0.3262, 0.3038]. On the figure 2(f), the absolute error of about 80% sampling point distributed in ±0.13. In a word, CS could achieve a higher CR and accuracy of the signal reconstruction for the original signal without noise from the experimental results.

4. Conclusions and Future Works

In this article, the potential of CS for compressing sparse data for SHM is investigated by using real sound vibration data on the aircraft. Through the all kinds of experiments and theoretical analysis, we found the specific CS technology for the SHM. From the simulation, this technology is not only able to ensure the accuracy of the data, but also improve the real-time data while reducing the load on the data transfer which provides a better way for the WSNs on the SHM applications. As a result, it has a good prospect application. Of course, this paper is not a perfect. The studies in the future are to improve the measurement matrix.

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References


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